

Using \mathcal{D}_{val} more than once

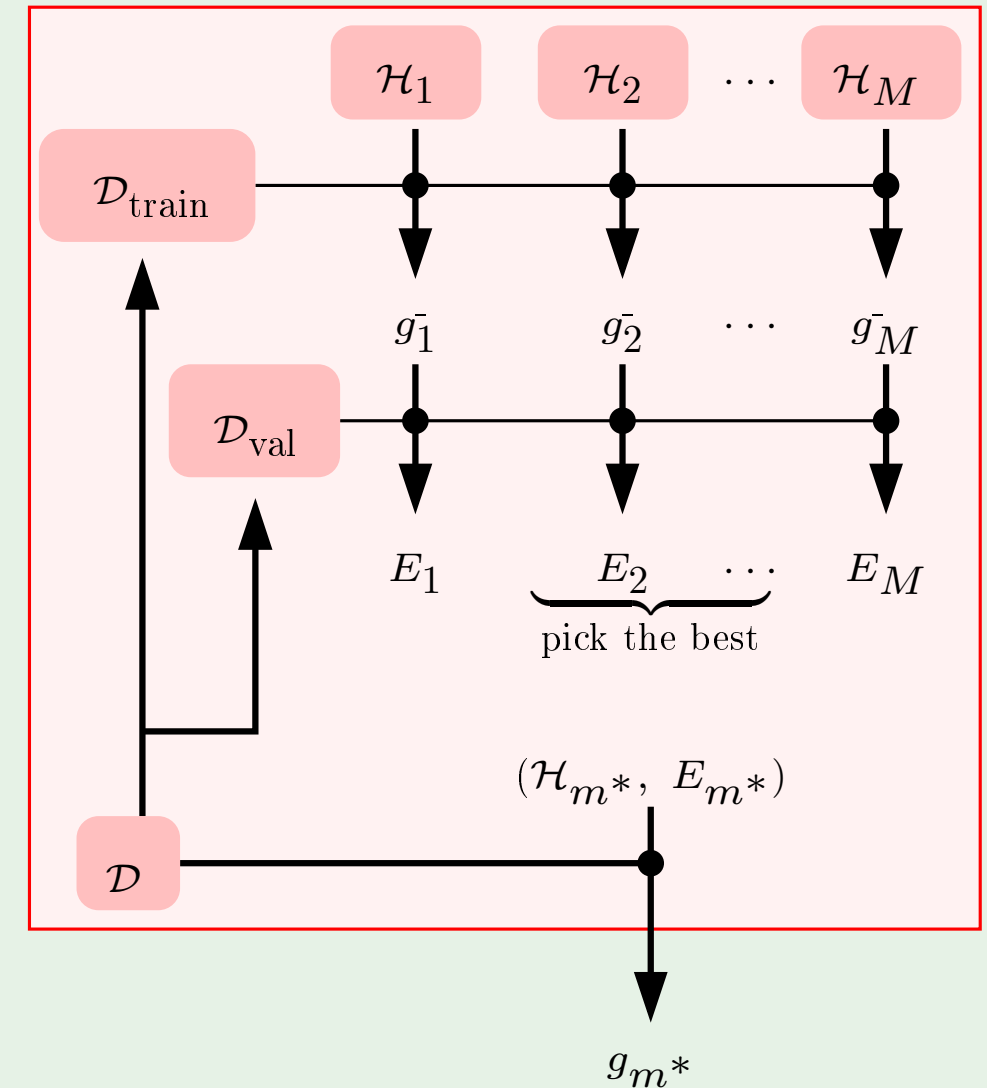
M models $\mathcal{H}_1, \dots, \mathcal{H}_M$

Use $\mathcal{D}_{\text{train}}$ to learn g_m^- for each model

Evaluate g_m^- using \mathcal{D}_{val} :

$$E_m = E_{\text{val}}(g_m^-); \quad m = 1, \dots, M$$

Pick model $m = m^*$ with smallest E_m

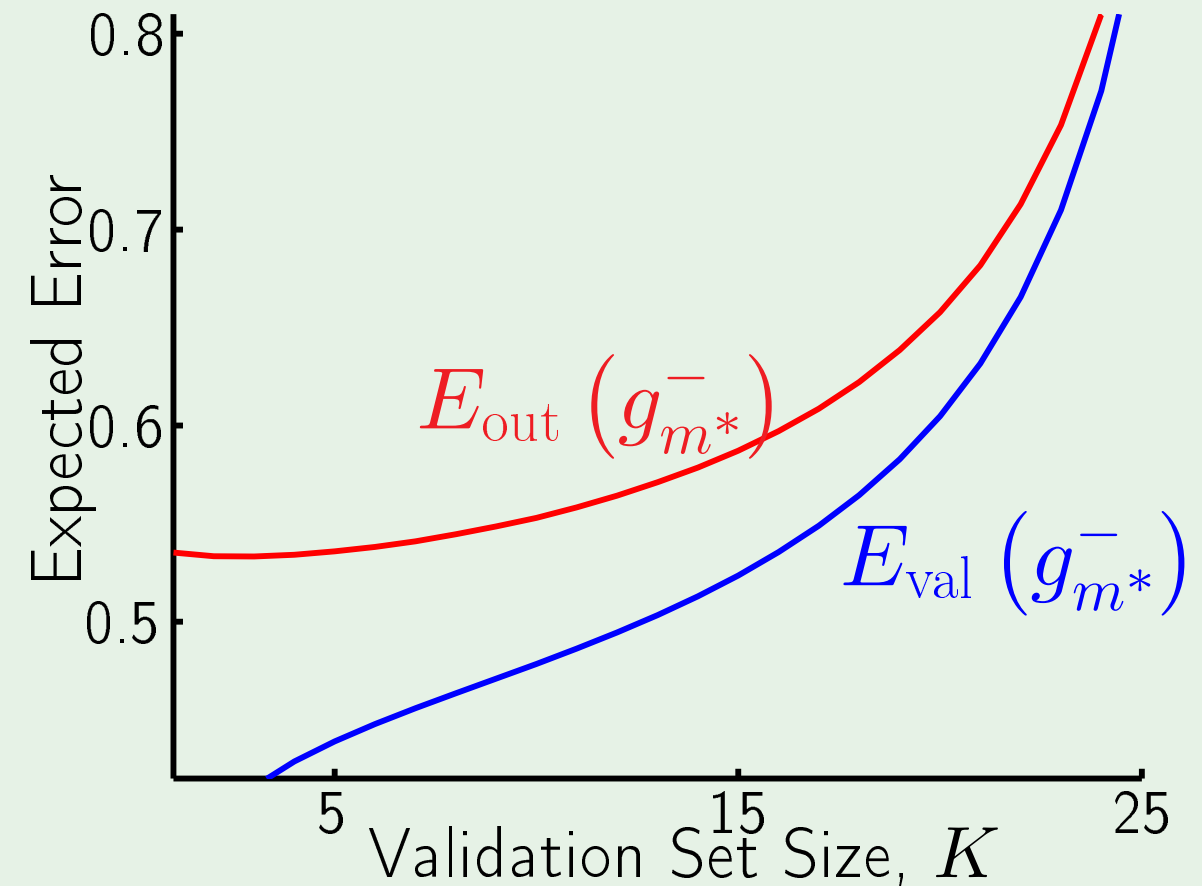


The bias

We selected the model \mathcal{H}_{m^*} using \mathcal{D}_{val}

$E_{\text{val}}(g_{m^*}^-)$ is a biased estimate of $E_{\text{out}}(g_{m^*}^-)$

Illustration: selecting between 2 models



How much bias

For M models: $\mathcal{H}_1, \dots, \mathcal{H}_M$

\mathcal{D}_{val} is used for “training” on the **finalists model**:

$$\mathcal{H}_{\text{val}} = \{g_1^-, g_2^-, \dots, g_M^-\}$$

Back to Hoeffding and VC!

$$E_{\text{out}}(g_{m^*}^-) \leq E_{\text{val}}(g_{m^*}^-) + O\left(\sqrt{\frac{\ln M}{K}}\right)$$

regularization λ early-stopping T

Data contamination

Error estimates: E_{in} , E_{test} , E_{val}

Contamination: Optimistic (deceptive) bias in estimating E_{out}

Training set: totally contaminated

Validation set: slightly contaminated

Test set: totally 'clean'