

Error measure

For each (\mathbf{x}, y) , y is generated by probability $f(\mathbf{x})$

Plausible error measure based on **likelihood**:

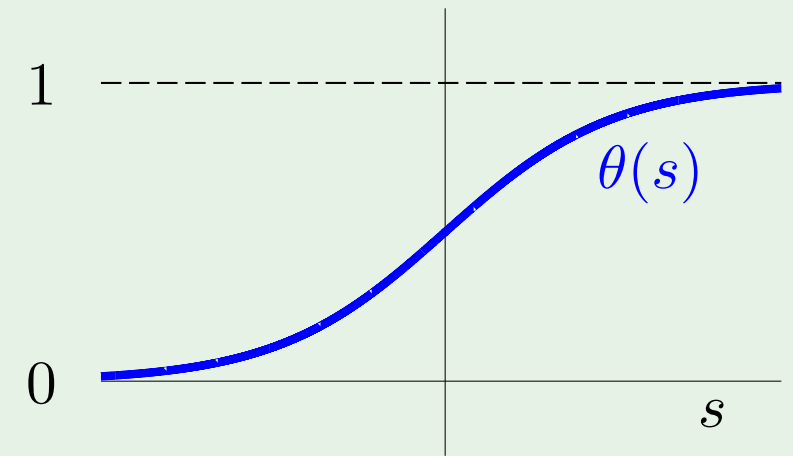
If $h = f$, how likely to get y from \mathbf{x} ?

$$P(y | \mathbf{x}) = \begin{cases} h(\mathbf{x}) & \text{for } y = +1; \\ 1 - h(\mathbf{x}) & \text{for } y = -1. \end{cases}$$

Formula for likelihood

$$P(y | \mathbf{x}) = \begin{cases} h(\mathbf{x}) & \text{for } y = +1; \\ 1 - h(\mathbf{x}) & \text{for } y = -1. \end{cases}$$

Substitute $h(\mathbf{x}) = \theta(\mathbf{w}^\top \mathbf{x})$, noting $\theta(-s) = 1 - \theta(s)$



$$P(y | \mathbf{x}) = \theta(y \mathbf{w}^\top \mathbf{x})$$

Likelihood of $\mathcal{D} = (\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)$ is

$$\prod_{n=1}^N P(y_n | \mathbf{x}_n) = \prod_{n=1}^N \theta(y_n \mathbf{w}^\top \mathbf{x}_n)$$

Maximizing the likelihood

Minimize

$$-\frac{1}{N} \ln \left(\prod_{n=1}^N \theta(y_n \mathbf{w}^\top \mathbf{x}_n) \right)$$

$$= \frac{1}{N} \sum_{n=1}^N \ln \left(\frac{1}{\theta(y_n \mathbf{w}^\top \mathbf{x}_n)} \right)$$

$$\left[\theta(s) = \frac{1}{1 + e^{-s}} \right]$$

$$E_{\text{in}}(\mathbf{w}) = \frac{1}{N} \sum_{n=1}^N \underbrace{\ln \left(1 + e^{-y_n \mathbf{w}^\top \mathbf{x}_n} \right)}_{e(h(\mathbf{x}_n), y_n)}$$

“cross-entropy” error